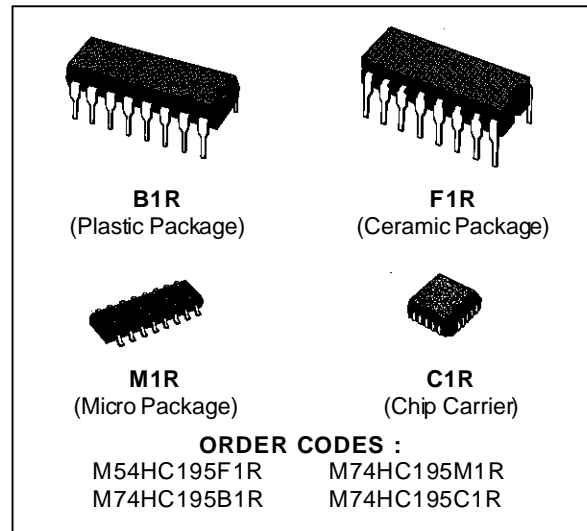


8 BIT PIPO SHIFT REGISTER

- HIGH SPEED
 $t_{PD} = 13 \text{ ns (TYP.) at } V_{CC} = 5 \text{ V}$
- LOW POWER DISSIPATION
 $I_{CC} = 4 \mu\text{A (MAX.) at } T_A = 25 \text{ }^\circ\text{C } 6 \text{ V}$
- HIGH NOISE IMMUNITY
 $V_{NIH} = V_{NIL} = 28 \% V_{CC} \text{ (MIN.)}$
- OUTPUT DRIVE CAPABILITY
 10 LSTTL LOADS
- SYMMETRICAL OUTPUT IMPEDANCE
 $|I_{OH}| = I_{OL} = 4 \text{ mA (MIN.)}$
- BALANCED PROPAGATION DELAYS
 $t_{PLH} = t_{PHL}$
- WIDE OPERATING VOLTAGE RANGE
 $V_{CC} \text{ (OPR)} = 2 \text{ V to } 6 \text{ V}$
- PIN AND FUNCTION COMPATIBLE
 WITH 54/74LS195



DESCRIPTION

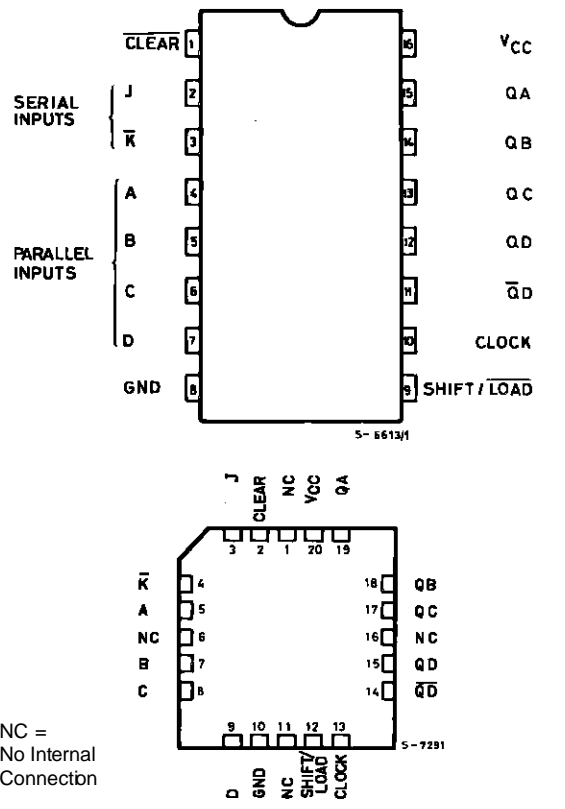
The M54/74HC195 is a high speed CMOS 4 BIT PIPO SHIFT REGISTER fabricated in silicon gate C²MOS technology. It has the same high speed performance of LSTTL combined with true CMOS low power consumption.

This shift register features parallel inputs, parallel outputs, J-K serial inputs, a SHIFT/LOAD control input, and a direct overriding CLEAR. This shift register can operate in two modes : Parallel Load ; Shift from QA towards QD.

Parallel loading is accomplished by applying the four bits of data, and taking the SHIFT/LOAD control input low. The data is loaded into the associated flip flops and appears at the outputs after the positive transition of the clock input. During parallel loading, serial data flow is inhibited. Serial shifting occurs synchronously when the SHIFT/LOAD control input is high. Serial data for this mode is entered at the J-K inputs. These inputs allow the first stage to perform as a J-K or TOGGLE flip flop as shown in the truth-table.

All inputs are equipped with protection circuits against static discharge transient excess voltage.

PIN CONNECTIONS (top view)



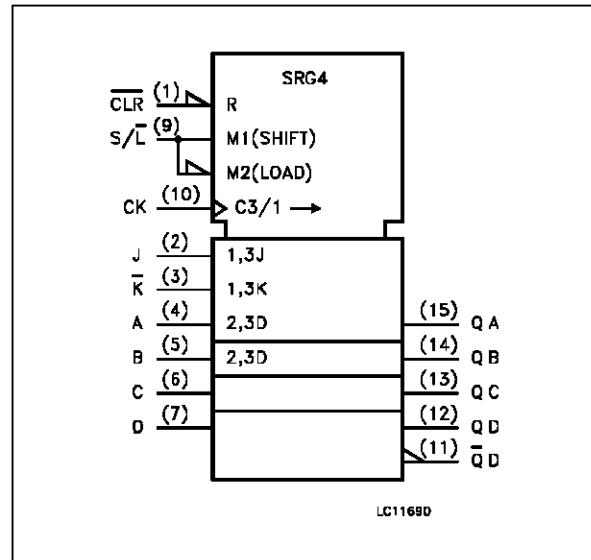
INPUT AND OUTPUT EQUIVALENT CIRCUIT



PIN DESCRIPTION

| PIN No | SYMBOL | NAME AND FUNCTION |
|----------------|---------------------------------|--|
| 1 | $\overline{\text{CLEAR}}$ | Reset Input (Active LOW) |
| 2 | J | First Stage J Input (Active LOW) |
| 3 | $\overline{\text{K}}$ | First Stage $\overline{\text{K}}$ Input (Active LOW) |
| 4, 5, 6, 7 | A to D | Parallel Data Input |
| 9 | SHIFT/ $\overline{\text{LOAD}}$ | Control Input |
| 10 | CLOCK | Clock Input (LOW to HIGH Edge-triggered) |
| 11 | $\overline{\text{QD}}$ | Inverted Output From The Last Stage |
| 15, 14, 13, 12 | QA to QD | Paralle Outputs |
| 8 | GND | Ground (0V) |
| 16 | V _{CC} | Positive Supply Voltage |

IEC LOGIC SYMBOL

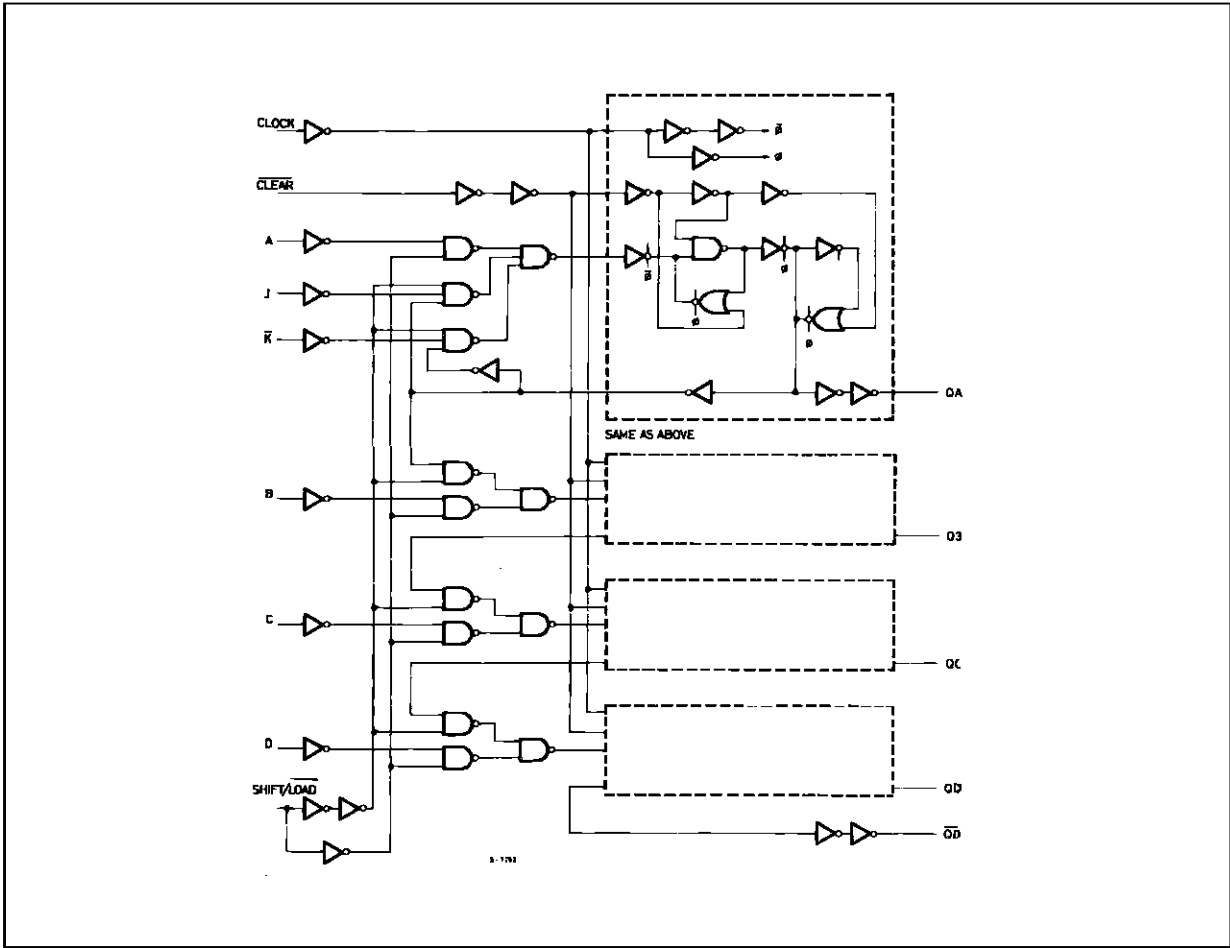


TRUTH TABLE

| CLEAR | SHIFT/LOAD | CLOCK | INPUTS | | | | | | OUTPUTS | | | | |
|-------|------------|-----------------------|--------|-----------------------|----------|---|---|---|-------------------------|-----|-----|-----|-------------------------|
| | | | SERIAL | | PARALLEL | | | | QA | QB | QC | QD | $\overline{\text{QD}}$ |
| | | | J | $\overline{\text{K}}$ | A | B | C | D | | | | | |
| L | X | X | X | X | X | X | X | X | L | L | L | L | L |
| H | L | | X | X | a | b | c | d | a | b | c | d | \overline{d} |
| H | H | $\overline{\text{L}}$ | X | X | X | X | X | X | QA0 | QB0 | QC0 | QD0 | $\overline{\text{QD0}}$ |
| H | H | | L | H | X | X | X | X | QA0 | QA0 | QBn | QCn | $\overline{\text{QCn}}$ |
| H | H | | L | L | X | X | X | X | L | QAn | QBn | QCn | $\overline{\text{QCn}}$ |
| H | H | | H | H | X | X | X | X | H | QAn | QBn | QCn | $\overline{\text{QCn}}$ |
| H | H | | H | L | X | X | X | X | $\overline{\text{QAn}}$ | QAn | QBn | QCn | $\overline{\text{QCn}}$ |

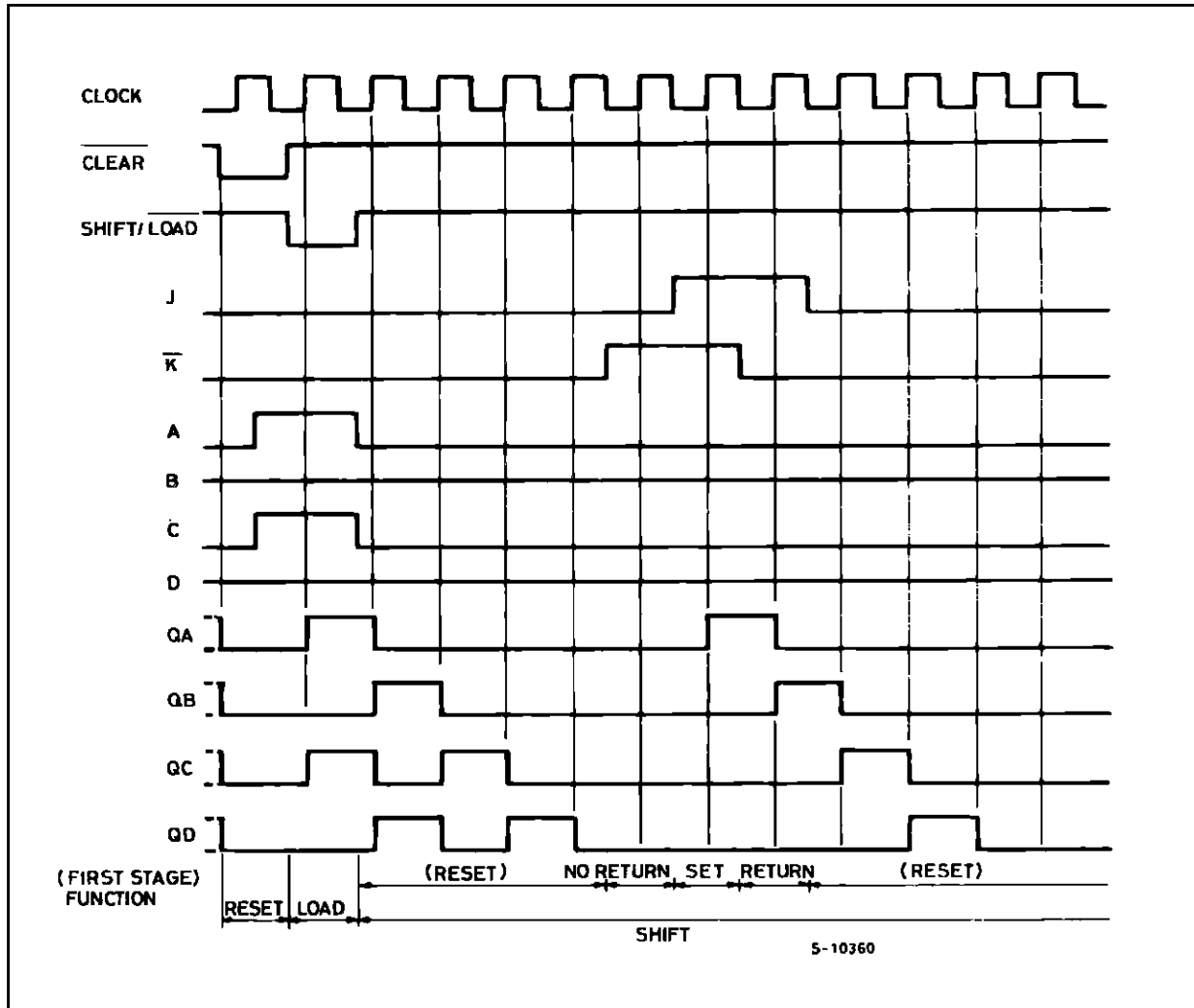
X: Don't Care: The level of QA, QB, QC, respectively, before the most recent positive transition of the clock.

LOGIC DIAGRAM



3-195

TIMING CHART



ABSOLUTE MAXIMUM RATINGS

| Symbol | Parameter | Value | Unit |
|-------------------------------------|--|-------------------------------|------|
| V _{CC} | Supply Voltage | -0.5 to +7 | V |
| V _I | DC Input Voltage | -0.5 to V _{CC} + 0.5 | V |
| V _O | DC Output Voltage | -0.5 to V _{CC} + 0.5 | V |
| I _{IK} | DC Input Diode Current | ± 20 | mA |
| I _{OK} | DC Output Diode Current | ± 20 | mA |
| I _O | DC Output Source Sink Current Per Output Pin | ± 25 | mA |
| I _{CC} or I _{GND} | DC V _{CC} or Ground Current | ± 50 | mA |
| P _D | Power Dissipation | 500 (*) | mW |
| T _{stg} | Storage Temperature | -65 to +150 | °C |
| T _L | Lead Temperature (10 sec) | 300 | °C |

Absolute Maximum Ratings are those values beyond which damage to the device may occur. Functional operation under these condition is not implied.

(*) 500 mW: ≡ 65 °C derate to 300 mW by 10mW/°C: 65 °C to 85 °C

RECOMMENDED OPERATING CONDITIONS

| Symbol | Parameter | Value | Unit | |
|---------------------------------|---|---|-----------------------------------|----|
| V _{CC} | Supply Voltage | 2 to 6 | V | |
| V _I | Input Voltage | 0 to V _{CC} | V | |
| V _O | Output Voltage | 0 to V _{CC} | V | |
| T _{op} | Operating Temperature: M54HC Series M74HC Series | -55 to +125 -40 to +85 | °C °C | |
| t _r , t _f | Input Rise and Fall Time | V _{CC} = 2 V V _{CC} = 4.5 V V _{CC} = 6 V | 0 to 1000 0 to 500 0 to 400 | ns |

DC SPECIFICATIONS

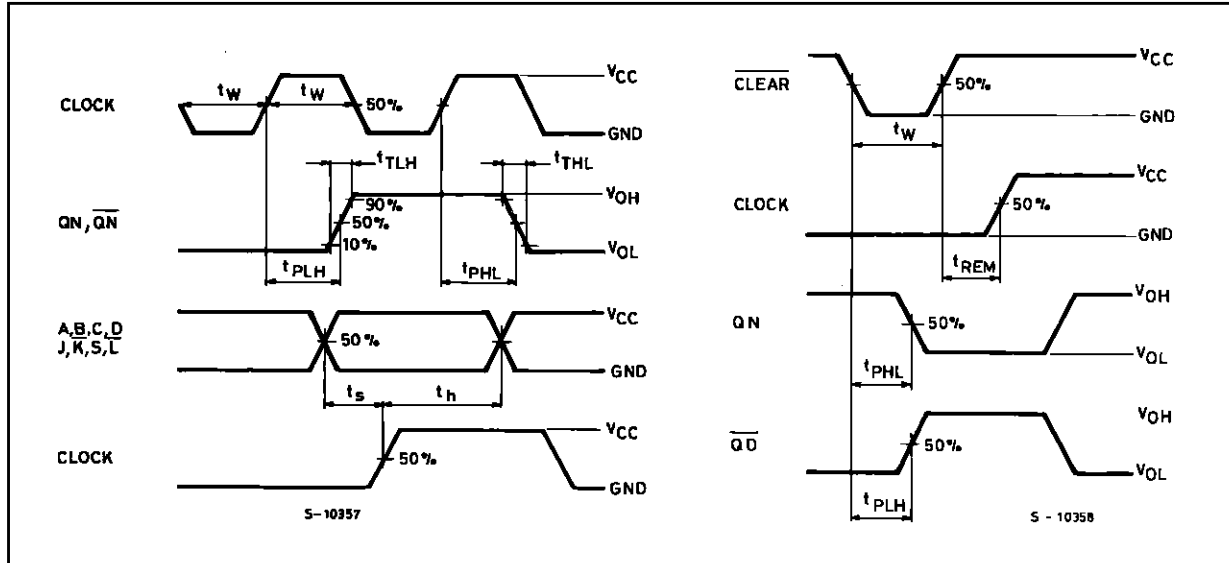
| Symbol | Parameter | Test Conditions | | Value | | | | | | Unit | | |
|-----------------|---------------------------|------------------------|--|---|-------------------------|------|----------------------|------|-----------------------|------|------|---|
| | | V _{CC} (V) | | T _A = 25 °C 54HC and 74HC | | | -40 to 85 °C 74HC | | -55 to 125 °C 54HC | | | |
| | | | | Min. | Typ. | Max. | Min. | Max. | Min. | | Max. | |
| V _{IH} | High Level Input Voltage | 2.0 | | 1.5 | | | 1.5 | | 1.5 | | V | |
| | | 4.5 | | 3.15 | | | 3.15 | | 3.15 | | | |
| | | 6.0 | | 4.2 | | | 4.2 | | 4.2 | | | |
| V _{IL} | Low Level Input Voltage | 2.0 | | | | 0.5 | | 0.5 | | 0.5 | V | |
| | | 4.5 | | | | 1.35 | | 1.35 | | 1.35 | | |
| | | 6.0 | | | | 1.8 | | 1.8 | | 1.8 | | |
| V _{OH} | High Level Output Voltage | 2.0 | V _I = V _{IH} or V _{IL} | I _O = -20 μA | 1.9 | 2.0 | | 1.9 | | 1.9 | V | |
| | | 4.5 | | | 4.4 | 4.5 | | 4.4 | | 4.4 | | |
| | | 6.0 | | | 5.9 | 6.0 | | 5.9 | | 5.9 | | |
| | | 4.5 | I _O = -4.0 mA | 4.18 | 4.31 | | 4.13 | | 4.10 | | | |
| | | 6.0 | | I _O = -5.2 mA | 5.68 | 5.8 | | 5.63 | | 5.60 | | |
| V _{OL} | Low Level Output Voltage | 2.0 | V _I = V _{IH} or V _{IL} | I _O = 20 μA | | 0.0 | 0.1 | | 0.1 | | 0.1 | V |
| | | 4.5 | | | | 0.0 | 0.1 | | 0.1 | | 0.1 | |
| | | 6.0 | | | | 0.0 | 0.1 | | 0.1 | | 0.1 | |
| | | 4.5 | | I _O = 4.0 mA | | 0.17 | 0.26 | | 0.33 | | 0.40 | |
| | | 6.0 | | | I _O = 5.2 mA | | 0.18 | 0.26 | | 0.33 | | |
| I _I | Input Leakage Current | 6.0 | V _I = V _{CC} or GND | | | ±0.1 | | ±1 | | ±1 | μA | |
| I _{CC} | Quiescent Supply Current | 6.0 | V _I = V _{CC} or GND | | | 4 | | 40 | | 80 | μA | |

AC ELECTRICAL CHARACTERISTICS ($C_L = 50$ pF, Input $t_r = t_f = 6$ ns)

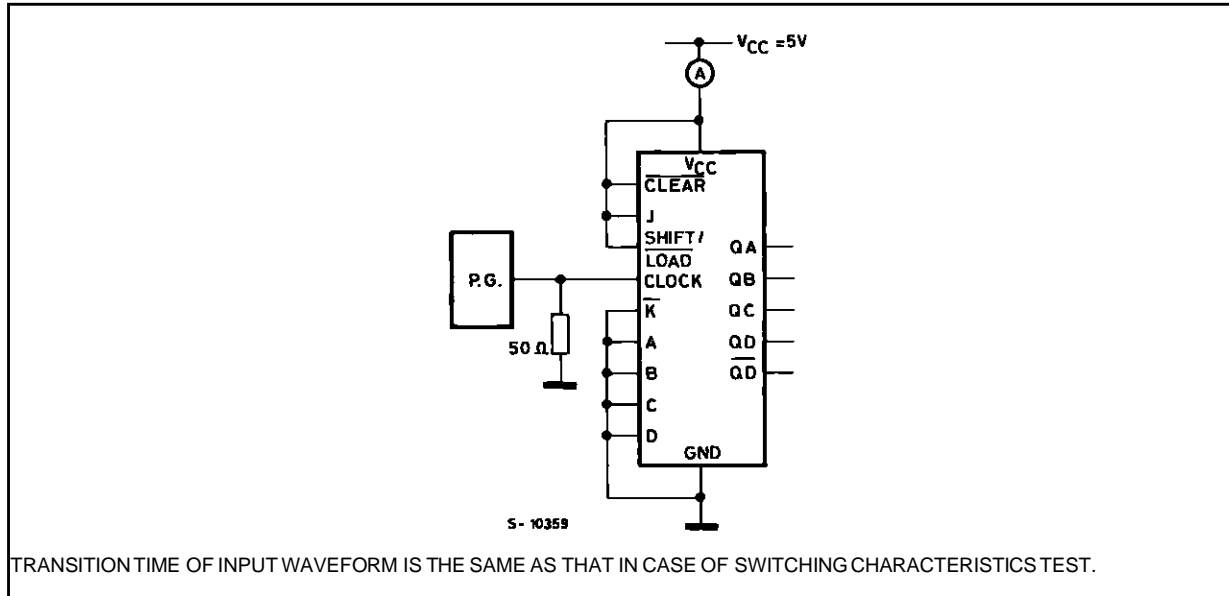
| Symbol | Parameter | Test Conditions | | Value | | | | | | Unit | |
|--|--|------------------------|--|---|------|------|----------------------|------|-----------------------|------|------|
| | | V _{CC} (V) | | T _A = 25 °C 54HC and 74HC | | | -40 to 85 °C 74HC | | -55 to 125 °C 54HC | | |
| | | | | Min. | Typ. | Max. | Min. | Max. | Min. | | Max. |
| t _{TLH} t _{THL} | Output Transition Time | 2.0 | | | 30 | 75 | | 95 | | 115 | ns |
| | | 4.5 | | | 8 | 15 | | 19 | | 23 | |
| | | 6.0 | | | 7 | 13 | | 16 | | 20 | |
| t _{PLH} t _{PHL} | Propagation Delay Time (CLOCK- Q _n , \overline{QD}) | 2.0 | | | 48 | 125 | | 155 | | 190 | ns |
| | | 4.5 | | | 16 | 25 | | 31 | | 38 | |
| | | 6.0 | | | 14 | 21 | | 26 | | 32 | |
| t _{PLH} t _{PHL} | Propagation Delay Time (CLEAR- Q _n , \overline{QD}) | 2.0 | | | 45 | 120 | | 150 | | 180 | ns |
| | | 4.5 | | | 15 | 24 | | 30 | | 36 | |
| | | 6.0 | | | 13 | 20 | | 26 | | 31 | |
| f _{MAX} | Maximum Clock Frequency | 2.0 | | 7.6 | 15 | | 6 | | 5 | | MHz |
| | | 4.5 | | 38 | 60 | | 30 | | 25 | | |
| | | 6.0 | | 45 | 71 | | 35 | | 30 | | |
| t _{W(H)} t _{W(L)} | Minimum Pulse Width (CLOCK) | 2.0 | | | 20 | 75 | | 95 | | 115 | ns |
| | | 4.5 | | | 5 | 15 | | 19 | | 23 | |
| | | 6.0 | | | 4 | 13 | | 16 | | 20 | |
| t _{W(L)} | Minimum Pulse Width (CLEAR) | 2.0 | | | 20 | 75 | | 95 | | 115 | ns |
| | | 4.5 | | | 5 | 15 | | 19 | | 23 | |
| | | 6.0 | | | 4 | 13 | | 16 | | 20 | |
| t _s | Minimum Set-up Time (PI) | 2.0 | | | 28 | 75 | | 95 | | 115 | ns |
| | | 4.5 | | | 7 | 15 | | 19 | | 23 | |
| | | 6.0 | | | 6 | 13 | | 16 | | 20 | |
| t _s | Minimum Set-up Time (J, K, S/L) | 2.0 | | | 28 | 75 | | 95 | | 115 | ns |
| | | 4.5 | | | 7 | 15 | | 19 | | 23 | |
| | | 6.0 | | | 6 | 13 | | 16 | | 20 | |
| t _h | Minimum Hold Time | 2.0 | | | | 0 | | 0 | | 0 | ns |
| | | 4.5 | | | | 0 | | 0 | | 0 | |
| | | 6.0 | | | | 0 | | 0 | | 0 | |
| t _{REM} | Minimum Removal Time | 2.0 | | | | 5 | | 5 | | 5 | ns |
| | | 4.5 | | | | 5 | | 5 | | 5 | |
| | | 6.0 | | | | 5 | | 5 | | 5 | |
| C _{IN} | Input Capacitance | | | | 5 | 10 | | 10 | | 10 | pF |
| C _{PD} (*) | Power Dissipation Capacitance | | | | 72 | | | | | | pF |

(*) C_{PD} is defined as the value of the IC's internal equivalent capacitance which is calculated from the operating current consumption without load. (Refer to Test Circuit). Average operating current can be obtained by the following equation. $I_{CC(opr)} = C_{PD} \cdot V_{CC} \cdot f_{IN} + I_{CC}$

SWITCHING CHARACTERISTICS TEST WAVEFORM

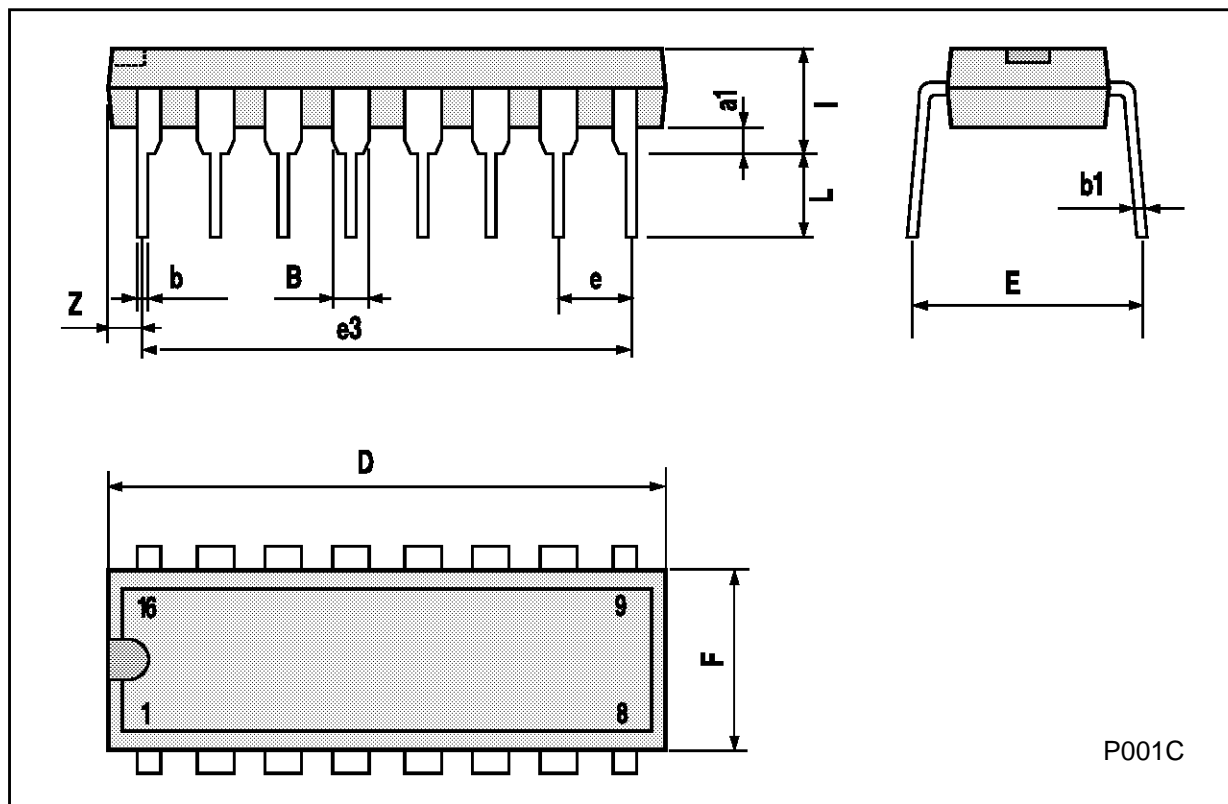


TEST CIRCUIT I_{CC} (Opr.)



Plastic DIP16 (0.25) MECHANICAL DATA

| DIM. | mm | | | inch | | |
|------|------|-------|------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| a1 | 0.51 | | | 0.020 | | |
| B | 0.77 | | 1.65 | 0.030 | | 0.065 |
| b | | 0.5 | | | 0.020 | |
| b1 | | 0.25 | | | 0.010 | |
| D | | | 20 | | | 0.787 |
| E | | 8.5 | | | 0.335 | |
| e | | 2.54 | | | 0.100 | |
| e3 | | 17.78 | | | 0.700 | |
| F | | | 7.1 | | | 0.280 |
| I | | | 5.1 | | | 0.201 |
| L | | 3.3 | | | 0.130 | |
| Z | | | 1.27 | | | 0.050 |



Ceramic DIP16/1 MECHANICAL DATA

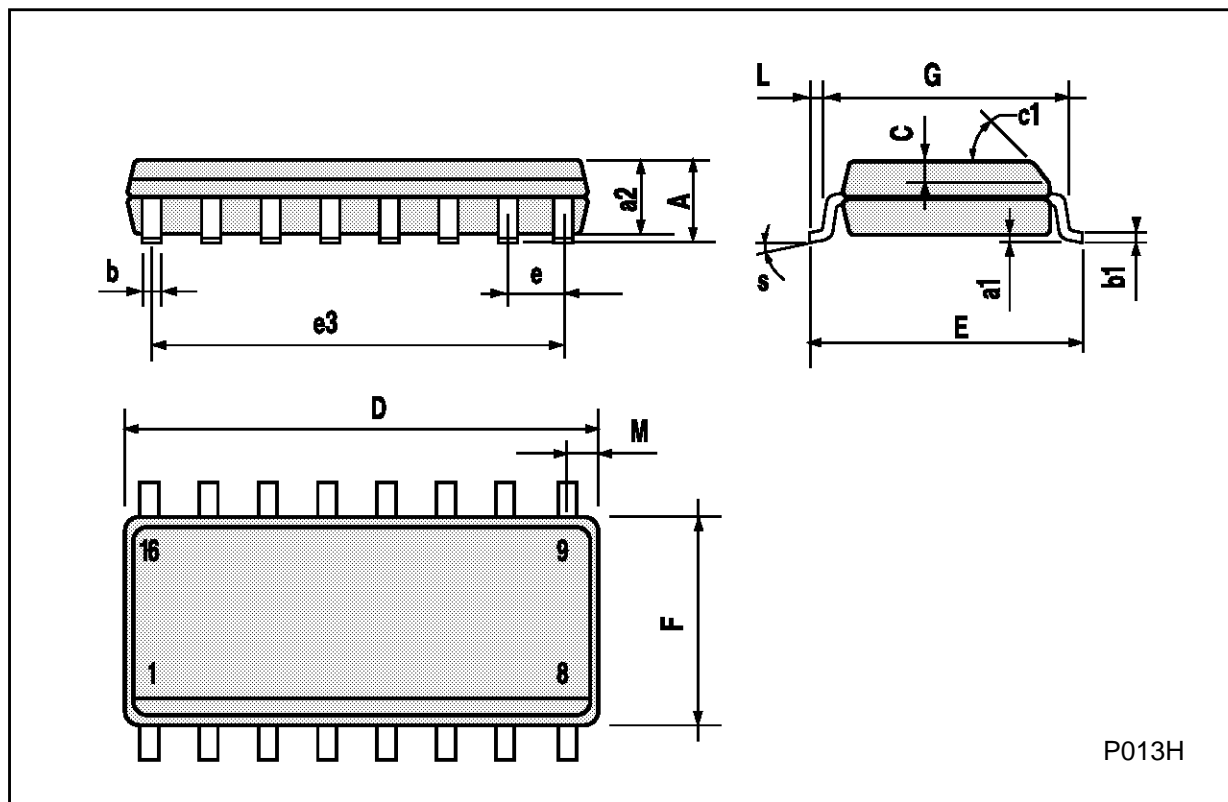
| DIM. | mm | | | inch | | |
|------|------|-------|------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | | | 20 | | | 0.787 |
| B | | | 7 | | | 0.276 |
| D | | 3.3 | | | 0.130 | |
| E | 0.38 | | | 0.015 | | |
| e3 | | 17.78 | | | 0.700 | |
| F | 2.29 | | 2.79 | 0.090 | | 0.110 |
| G | 0.4 | | 0.55 | 0.016 | | 0.022 |
| H | 1.17 | | 1.52 | 0.046 | | 0.060 |
| L | 0.22 | | 0.31 | 0.009 | | 0.012 |
| M | 0.51 | | 1.27 | 0.020 | | 0.050 |
| N | | | 10.3 | | | 0.406 |
| P | 7.8 | | 8.05 | 0.307 | | 0.317 |
| Q | | | 5.08 | | | 0.200 |



P053D

SO16 (Narrow) MECHANICAL DATA

| DIM. | mm | | | inch | | |
|------|------------|------|------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | | | 1.75 | | | 0.068 |
| a1 | 0.1 | | 0.2 | 0.004 | | 0.007 |
| a2 | | | 1.65 | | | 0.064 |
| b | 0.35 | | 0.46 | 0.013 | | 0.018 |
| b1 | 0.19 | | 0.25 | 0.007 | | 0.010 |
| C | | 0.5 | | | 0.019 | |
| c1 | 45° (typ.) | | | | | |
| D | 9.8 | | 10 | 0.385 | | 0.393 |
| E | 5.8 | | 6.2 | 0.228 | | 0.244 |
| e | | 1.27 | | | 0.050 | |
| e3 | | 8.89 | | | 0.350 | |
| F | 3.8 | | 4.0 | 0.149 | | 0.157 |
| G | 4.6 | | 5.3 | 0.181 | | 0.208 |
| L | 0.5 | | 1.27 | 0.019 | | 0.050 |
| M | | | 0.62 | | | 0.024 |
| S | 8° (max.) | | | | | |



P013H

PLCC20 MECHANICAL DATA

| DIM. | mm | | | inch | | |
|------|------|------|-------|-------|-------|-------|
| | MIN. | TYP. | MAX. | MIN. | TYP. | MAX. |
| A | 9.78 | | 10.03 | 0.385 | | 0.395 |
| B | 8.89 | | 9.04 | 0.350 | | 0.356 |
| D | 4.2 | | 4.57 | 0.165 | | 0.180 |
| d1 | | 2.54 | | | 0.100 | |
| d2 | | 0.56 | | | 0.022 | |
| E | 7.37 | | 8.38 | 0.290 | | 0.330 |
| e | | 1.27 | | | 0.050 | |
| e3 | | 5.08 | | | 0.200 | |
| F | | 0.38 | | | 0.015 | |
| G | | | 0.101 | | | 0.004 |
| M | | 1.27 | | | 0.050 | |
| M1 | | 1.14 | | | 0.045 | |



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